

Prof. dr. eng. DANIELA TARNITA
Curriculum vitae



Professor of Mechanisms Theory; Strength of Materials; Biomechanics;

Head of Doctoral School in Mechanical Engineering, University of Craiova;

Head of Biomechanics Research Laboratory, INCESA Research Centre, University of Craiova;

Head of Research Centre in Mechanical Engineering, University of Craiova;

Fields and research topics:

- Biomechanics;
- Biomedical engineering;
- Robotics;
- Numerical Simulations and Analysis of stresses and deformations for human musculoskeletal system using Finite Element Method;
- Intelligent materials and their applications in medical field;
- Design and optimization for orthopedic devices and implants and for rehabilitation devices.
- Human gait analysis (normal and pathological)
- Nonlinear dynamics applied in biomechanics

1. Studies:

Institution	Period	Obtained degree
”Carol I” High school Craiova	Sept. 1973-June 1977	Baccalaureate diploma
Faculty of Mechanics, Univ. of Craiova	Sept. 1977-July 1982	Mechanical engineer
Faculty of Mechanics, Univ. of Craiova	Dec.1990- June 1996	Ph.D. diploma in Technical Sciences
Faculty of Economic Science, Univ. of Craiova	Sept. 1990-July 1995	Economic informatics diploma

2. Scientific title: Ph. D. Eng. In Engineering Sciences

3. Proficiency in foreign languages: English, French

4. Professional Experience:

Institution	Period	Function
University of Craiova	Sept. 1984-Sept. 1991	Assist.
University of Craiova	Sept. 1991-Jan. 1997	Lecturer
University of Craiova	Jan.1997-Sept. 2001	Assist. Prof.
University of Craiova	Sept.2001-present	Professor

Professional mobilities:

Institution	Period	Activity
Princeton University, SUA	1 week, 2016	Visiting Professor
Princeton University, SUA	3 weeks, 2015	Visiting Professor
Harvard University, SUA	3 weeks, 2009	Documentation-research
Harvard University, SUA	3 weeks, 2008	Documentation-research
Duisburg-Essen University, Germany	3 weeks, 2007	Documentation-research
Duisburg -Essen University, Germany	1 week, 2005	Visiting Professor
Germany	1 week, 2004	Socrates Mobility

5. Awards for patents:

1. **24 gold medals** for patents in the medical field obtained at **International Exhibitions of Creativity and Innovation in period 2013-2018.**
2. **The Best International Invention of Social and Quality of Life - Salon International de inventii, IPITEX, Bangkok, feb. 2018**
3. **Special Honour of Invention** – awarded by **Toronto International Society of Innovation & Advanced Skills, Canada, 2018;**
4. **Genius Award & Gold medal** – awarded by **Citizen Innovation Association, Singapore, 2018.**
5. **British Innovation Award** – awarded by **Association of British Inventors and Innovations, Great Britain, 2018;**
6. **Special Award and Gold Medal** – awarded by **Malaysian Research & Innovation Society, Malaysia, 2018.**
7. **Honor of Invention and Gold Medal** – awarded by **World Invention Intellectual Property Associations, 2018;**
8. **Award for International Innovation Achievements** - awarded by **Haller Pro Invention Foundation, Polonia, 2018.**
9. **Medicine Award - EUROINVENT-** European Exhibition of Creativity and Innovation -May 2014
10. **Woman Inventor Award - EUROINVENT-** European Exhibition of Creativity and Innovation -May 2013
11. **Grand Prize "Eliza Leonida Zamfirescu - A Romanian woman - the first engineer woman in the world" -** International Exhibition of Creativity and Innovation PROINVENT - March 2013
12. **Cyber Future Award –EUROINVENT, may, 2017**
13. **Trophy “Academician Ana Aslan” – Inventions Exhibition CADET 2017.**
14. **Great Trophy awarded by Inventors Forum of Irak, 2017.**
15. **First prize and Gold Medal awarded by the Polytechnic University of Bucharest, 2017.**
16. **Three Excellence Awards for patents at International Salons of Creativity and Innovation**
17. **Gold Medal- China International Exhibition of Inventions – China (Shanghai) -may 2017**
18. **Gold Award- Malaysia Research and Innovation Society- Kuala Lumpur, Malaysia, april 2017**
19. **Gold Medal – Salon Inventii Katowice, INTARG 2017, Katowice, Poland, iunie, 2017**
20. **Gold Medal – Salon Inventii, Croatia, nov 2017.**
21. **Gold Medal – Salon Inventii INFOINVENT, Chisinau, Moldova, nov. 2017**

Awards for papers:

1. The Industrial Robot Innovation Award 2008 Highly Commended, 2008 for the paper: Bizdoacă, N., Tarniță, D.N., Tarniță, Daniela, Application of smart materials: bionics modular adaptive implants, Advances in Mobile Robotics, ISBN-10 981-283-576-8 World Scientific Publishing Co.Pte.Ltd, pag 190-198.

2. Award of Excellence for the paper Catana M., Tarnita Daniela., Tarnita D.N., Modeling, Simulation and Optimization of a Human Knee Orthotic Device, Applied Mechanics and Materials, Vol. 371 (2013), pp 549-553, Trans Tech Publications, Switzerland.

3. Award of UEFISCDI, 2014 for the paper: Tarnita, Daniela, Marghitu, D., Analysis of a hand arm system, Robotics and Computer-Integrated Manufacturing, Vol. 29, Issue 6, December 2013, Pages 493–501

4. The Bronze Best Research Paper Award pentru lucrarea: Tarnita D., Georgescu, M, Geonea, I, Petcu, A., Tarnita, D.-N., Nonlinear Analysis of Human Ankle Dynamics – awarded by IFToMM and International Committee Award for MESROB 2018, Cassino, Italy, 2018

5. Award of UEFISCDI, for the paper: Tarnita, D., Marghitu, D, Nonlinear dynamics of normal and osteoarthritic human knee, Proceedings of the Romanian Academy, pp. 353-360, 2017

6. Patents:

1. **System of modular plates for the osteosynthesis of long bone fractures and method for using the same**

Patent Number: **RO126084-A2; RO126084-B1, 2013**

Patent Assignee: UNIV CRAIOVA

Inventor(s): **Tarnita, D., Tarnita, D.N., Bizdoaca, N G.**

2.Modular-adaptive central-medullary orthopaedic nail to be used in treatment of diaphyseal fractures of long bones

Patent Number: **RO127375-A2; RO127375-B1, 2013**

Patent Assignee: UNIV CRAIOVA

Inventor(s): **Tarnita, D.**, Cismaru F., Tarnita, D.N.; et al.

3.Adaptive modular lattice based on intelligent materials such as nitinol, used for the reduction of a fracture and proper immobilization of osseous fragments in the case of long bone fractures

Patent Number: **RO127483-A2 din 30.12. 2013**

Patent Assignee: UNIV CRAIOVA

Inventor(s): Bizdoaca, N G; Tarnita, D.; Danoiu S; et al.

4.Artificial hand-forearm system used for carrying out an upper human limb prosthesis

Patent Number: RO128911-A2

Inventor(s): BERCEANU C R; **TARNITA D.**

5.Ball and socket type joint for elbow prosthesis,

Patent Number: RO129147-A0, /2018

Inventor(s): **TARNITA D N; Tarnita Daniela, BOBORELU C; POPA D L.**

6.Tuşaliu, P.,**Tarniță, D.**,s.a.- Device for Modeling High Voltage Distribution on 750KV Class Insulation Chains -**Certificat de inovator nr.253**, Ministry of Education, 30 sept., 1985.

Applications for patents:

1.Orthotic device used for osteoarthritic knee joint,

Patent assignee: **University of Craiova,**

Inventors: **Catana Marius, Tarnita Daniela, Tarnita Danut Nicolae,**

Application number A00821 /2013.

2. Device for progressive rehabilitation of human joints used in orthotic systems,

Inventors: **Petcu Alin Ionel, Tarniță Daniela, Tarniță Dănuț Nicolae,**

Application Patent Number OSIM: A0081/ 14.02.2017.

3.MODULAR-ADAPTIV STEM FOR TOTAL HIP PROSTHESIS, BASED ON INTELLIGENT MATERIALS

Inventors: Tarnita Danut Nicolae, **Daniela Tarnita,**

Application Patent Number: A01023 / 2016

4.Modular exoskeleton for applications in recovery of human lower limb,

Inventors: Geonea Ionut, **Daniela Tarnita,**

Application Patent Number. A00047/30.01. 2017

7. Publications

More than 150 papers in peer reviewed journals and conferences proceedings on different aspects of Biomechanics, Intelligent materials and their applications in medical field and robotics; Design and optimization for orthopaedic implants, Mechanisms and Machines Theory, Robotics.

Editor of the book „Current Solutions in Mechanical Engineering” (576 pages) published in Trans Tech Publishing House, Suizzerland, Volume 823 of Applied Mechanics and Materials, ISSN print 1660-9336, ISSN cd 1660-9336, ISSN web 1662-7482

7.1. Papers (selection)

7.1.1 Papers in ISI journals

1. **Tarnita, D.**, D-B MARGHITU, **Nonlinear dynamics of normal and osteoarthritic human knee**, Proceedings of the Romanian Academy, pp. 353-360, 2017.
2. Geonea, I., **Tarnita, D.**, **Design and evaluation of a new exoskeleton for gait rehabilitation**, Mechanical Sciences, 8(2), pp 307-322, 2017.

3. **Tarnita, D.,** Calafeteanu, D., Geonea, I., Petcu, A., Tarnita, D.N., **Effects of malalignment angle on the contact stress of knee prosthesis components, using finite element method,** *Rom J Morphol Embryol*, 58(3), pp. 831-836, 2017.
4. **Tarnita, Daniela,** Wearable sensors used for human gait analysis, *Rom J Morphol Embryol* 2016, 57(2), pp 373-382.
5. **Tarnita, Daniela,** Tarnita, D.N., **Experimental measurement of flexion-extension movement in normal and corpse prosthetic elbow joint,** *Rom J Morphol Embryol* 2016, 57(1):145–151.
6. DN Tarniță, **Daniela Tarniță,** D Grecu, D Calafeteanu, B Căpitănescu, **New technical procedure involving Achilles tendon rupture treatment through transcutaneous suture,** *Rom J Morphol Embryol* 2016, 57(1):211–214.
7. **Tarnita, Daniela,** Marghitu, D., **Analysis of a hand arm system,** *Robotics and Computer-Integrated Manufacturing*, Vol. 29, Issue 6, Pages 493–501, <http://dx.doi.org/10.1016/j.rcim.2013.06.001>, 2013.
8. **Tarnita, Daniela,** Catana, M., Tarnita, D.N., **Experimental measurement of flexion-extension movement in normal and osteoarthritic human knee,** *Romanian Journal of Morphology and embryology*, 54(2):309–313, 2013, <http://www.rjme.ro/RJME/resources/files/540213309313.pdf>.
9. **Tarnita, D.,** Tarnita, D.N., Oprea, B., Samide A., **Electrochemical study on corrosion resistance in physiological media of nitinol wire used as bioimplant,** *Digest Journal of Nanomaterials and Biostructures*, Vol. 8, No. 1, 2013, p. 35 – 41, http://www.chalcogen.ro/35_Tarnita.pdf.
10. **Tarnita, D.,** Berceanu, C., Tarnita, C., **The three-dimensional printing—a modern technology used for biomedical prototypes,** *Materiale plastice*, no.47, nr.3, pp 328-334, 2010, www.revmaterialeplastice.ro.
11. **Tarnita, D.,** Tarnita, D.N., Tarnita, R., Berceanu, C., Cismaru, F., **Modular adaptive bone plate connected by Nitinol staple,** *Materialwissenschaft und Werkstofftechnik, Materials Science and Engineering Technology, Special Edition Biomaterials, Wiley-Vch*, 41 (12), 1070-1080, DOI 10.1002/mawe.201000711, 2010, <http://onlinelibrary.wiley.com/doi/10.1002/mawe.201000711>.
12. **Tarnita D.,** Bolcu, D., Berceanu, C., Cismaru, F., **Theoretical and experimental studies for an orthopedic staple made up Nitinol,** *Journal of Optoelectronics and Advanced Materials*, Vol.12, No.11, pp. 2323–2332, 2010, www.joam.inoe.ro/index.php.
13. **Tarnita D.,** Boborelu, C., Popa, D., Rusu, L., **The three-dimensional modeling of the complex virtual human elbow joint,** *Romanian Journal of Morphology and embryology*, Vol 51, No.3, pp 489-495, 2010, <http://www.rjme.ro/RJME/resources/files/510310489495.pdf>.
14. **Tarnita, D.,** Tarnita, D.N., Popa D., Grecu, D., Niculescu, D., **Numerical simulations of human tibia osteosynthesis using modular plates based on Nitinol staples,** *Romanian Journal of Morphology and embryology*, Vol 51, No.1, pp 145-150, 2010, <http://www.rjme.ro/RJME/resources/files/510110145150.pdf>.
15. **Tarnita, D.,** Tarnita, D.N., Hacman, L., Copilusi, C., Berceanu, C., Cismaru, F., **In vitro experiment of the modular orthopedic plate based on Nitinol, used for human radius bone fractures,** *Romanian Journal of Morphology and embryology*, Vol 51, No2, pp. 315-320, 2010, <http://www.rjme.ro/RJME/resources/files/510210315320.pdf>.
16. **Tarnita, D.,** Tarnita, D.N., Bizdoaca, N., Popa, D., **Contributions on the dynamic simulation of the virtual model of the human knee joint,** *Materialwissenschaft und Werkstofftechnik, Materials Science and Engineering Technology, Special Edition Biomaterials, Wiley-Vch., ISSN 0933-5137, Vol.40, No.1-2,* 2009, pp73-81, <http://onlinelibrary.wiley.com/doi/10.1002/mawe/>.
17. **Tarnita, D.,** Tarnita, D.N., Bizdoaca, N., C Tarnita, C. Berceanu, C. Boborelu, **Modular adaptive bone plate for humerus bone osteosynthesis,** *Romanian Journal of Morphology and embryology*, Vol. 50(3), pp. 447-452 ISSN 1220-0522, 2009, <http://www.rjme.ro/RJME/resources/files/500309447452.pdf>.
18. **Tarnita, D.,** Tarnita, D. N., et al., **Properties and Medical Applications of Shape memory Alloys;** *Romanian Journal of Morphology and embryology*, Vol. 50. No.1, pp.15-22, 2009 (40 citations), <http://www.rjme.ro/RJME/resources/files/500109015021.pdf>.
19. **Tarnita, D.,** Popa, D., Tarnita, D. N., Grecu, D., **CAD method for 3D model of the tibia bone and study of stresses using the finite element method,** *Romanian Journal of Morphology and Embryology*, Vol. 47. No.2, pp.181-186, ISSN 1220-0522, 2006, <http://www.rjme.ro/RJME/resources/files/470206181186.pdf>.
20. Bizdoaca, N., **Tarnita, D.,** Tarnita, D. N., **Modular adaptive implant based on smart materials,** *Romanian Journal of Morphology and embryology*, Vol.49. No.4, pp.507-512, 2008, <http://www.rjme.ro/RJME/resources/files/490408507512.pdf>.
21. **Tarniță, D.,** Popa, D., Tarniță, D.N., Grecu, D., Negru, M., **The virtual model of the prosthetic tibial components,** *Romanian Journal of Morphology and embryology*, 2006, 47(4):339–344, <http://www.rjme.ro/RJME/resources/files/470406339344.pdf>.

22. Tarniță, D.N., **Tarniță, D.**, Popa, D., **Analysis of stress and displacements of phalanx bone with the finite element method**, in Romanian Journal of Morphology and embryology, vol. 46 no. 3, pp 189-192, 2005, <http://www.rjme.ro/RJME/resources/files/460305189191.pdf>
23. Popa, D., Tarnita, D.N., **Tarnita, D.**, Grecu, D., **The generation of the three-dimensional model of the human knee joint**, in Romanian Journal of Morphology and embryology, vol.46 no.4, pp.3-6, 2005,<http://www.rjme.ro/RJME/resources/files/460405279281.pdf>.

7.1.2 Papers in Proceedings ISI, Scopus, and other BDI Journals

1. **Daniela Tarnita**, I Geonea, A. Petcu, D.N. Tarnita, Numerical Simulations and Experimental Human Gait Analysis Using Wearable Sensors, **New Trends in Medical and Service Robots, Springer Publishing House**, DOI:10.1007/978-3-319-59972-4_2, pp.289-304, **2018**.
2. **Tarniță, Daniela**, I Geonea, A. Petcu, D.N. Tarnita, Experimental Characterization of Human Walking on Stairs Applied to Humanoid Dynamics, **Advances in Robot Design and Intelligent Control, Springer**, 293-301, 2016.
3. **Daniela Tarnita**, Marius Georgescu, Dan Tarnita, **Applications of Nonlinear Dynamics to Gait Analysis on Plane & Inclined Treadmill**, New Trends in Medical and Service Robots, Springer Publishing House, Vol 39, pp. 59-73, 2016.
4. **Daniela Tarnita**, M Catana, D.N. Tarnita, **Design and Simulation of an Orthotic Device for Patients with Osteoarthritis**, pp. 61-77, New Trends in Medical and Service Robots, Springer Publishing House, ISBN 978-3-319-23832-6, pp 61-77, 2016
5. **Daniela Tarnita**, D. Popa, C. Boborelu, N. Dumitru, D. Calafeteanu*, D.N. Tarnita, **Experimental Bench Used to Test Human Elbow Endoprosthesis**, New Trends in Mechanism and Machine Science, Vol 24 (2015), pp. 669-677, Springer International Publishing, Editor: Paulo Flores (https://link.springer.com/chapter/10.1007%2F978-3-319-09411-3_71).
6. N. Dumitru, C. Copilusi, I. Geonea, **D. Tarnita**, I. Dumitrache, **Dynamic Analysis of an Exoskeleton New Ankle Joint Mechanism**, New Trends in Mechanism and Machine Science Mechanisms and Machine Science Vol 24, 2015, Springer International Publishing, pp 709-717, DOI 10.1007/978-3-319-09411-3-75.
7. **Daniela Tarnita**, Marius Catana, Dan Tarnita, **Contributions on the modeling and simulation of the human knee joint with applications to the robotic structures**, In “**New Trends on Medical and Service Robotics: Challenges and Solutions**”, Mechanisms and Machine Science 20, DOI: 10.1007/978-3-319-05431-5_19, pp. 283-297, Springer Verlag, 2014, editors: A.Rodic, Hannes Bleuler, Doina Pisla
8. **Daniela Tarnita**, C. Berceanu, **Comparison of Human and Artificial Finger Movements**, In **New Trends in Medical and Service Robots**, Mechanisms and Machine Science Vol 16, 2013, pp 221-235
9. **Tarnita, Daniela**, Popescu, I., Dan Marghitu, **Creating Artistic Curves with Planar Mechanisms**, **ISI Proceedings of SYROM 2013, ed. Springer, 2013** pp.233-240, Mechanisms and Machine Science, Vol. 18, ISBN:978-3-319-01844-7.
10. **Daniela Tarnita**, Marius Catana, Dan Tarnita, **Nonlinear Analysis of Osteoarthritis Process in Virtual Human Knee Joint**, **ISI Proceedings of SYROM 2013, ed. Springer**, pp. 225-232, **2013**, Mechanisms and Machine Science, Vol.18, ISBN:978-3-319-01844-7, ISBN 978-3-319-01845-4 (eBook), http://link.springer.com/chapter/10.1007/978-3-319-01845-4_23?no-access=true.
11. **Tarnita, Daniela**, Popa, D., Dumitru, N., Tarnita, D.N., Mărcușanu, V., Berceanu, C*, **Numerical Simulations of the Human Knee Joint**, chapter in “**New Trends in Mechanisms Science: Analysis and Design**”, pp 309-317, Springer Publishing House, 2010, ISBN 978-90-481-9688-3.
12. Berceanu, C., **Tarnita, Daniela**, Dumitru, S., Filip, D., **Forward and Inverse Kinematics Calculation for an Anthropomorphic Robotic Finger**, in “**New Trends in Mechanisms Science: Analysis and Design**”, pp 335-342, **Springer Publishing House**, ISBN 978-90-481-9688-3, 2010, http://link.springer.com/chapter/10.1007/978-90-481-9689-0_39?no-access=true.
13. Bizdoacă, N., Tarniță, D.N., **Tarniță, Daniela**, **Application of smart materials: bionics modular adaptive implants**, Advances in Mobile Robotics, ISBN-10 981-283-576-8 **World Scientific Publishing Co.Pte.Ltd**, pp. 190-198.
14. **Tarnita, Daniela**, Tarnita, D.N., Bizdoaca, N., Cismaru, F., **Modular orthopedic devices based on shape memory alloys**, ISI Proceedings Ed. Springer, The 10th IFToMM International Symposium on Science of Mechanisms and Machines, SYROM’09, pp.709-721, 2009.
15. Degeratu, S., **Tarnita, D.**, et al, **Experimental investigation of a barrier structure based on a Shape Memory Alloy actuator**, OPTIM 2017 IEEE Conference, 102-108, mai 2017

16. D. Calafeteanu, **Daniela Tarnita**, D. N. Tarnita, **Numerical Simulations of 3D Model of Knee-prosthesis Assembly with Antero-posterior Tibial Slope**, IFToMM Congres, Taipei, 2015, oct, DOI Number: 10.6567/IFToMM.14TH.WC.OS1.008
17. **Tarnita, Daniela**, Catana, M., Tarnita, D.N., **Modeling and Finite Element Analysis of the Human Knee Joint Affected by Osteoarthritis**, Key Engineering Materials Vol. 601 (2014) pp 147-150, <http://www.scientific.net/KEM.601.147>.
18. **Tarnita Daniela**, Calafeteanu D., Matei I, Tarnita D.N, **Experimental Measurement of Flexion-Extension in Normal and Osteoarthritic Knee During Sit-to-Stand Movement**, Applied Mechanics and Materials Vol. 658 (2014) pp 520-525, www.scientific.net/AMM.658.520.
19. **Daniela Tarnita**, Marius Catana, Dan Tarnita, **Modeling and Finite Element Analysis of the Human Knee Joint Affected by Osteoarthritis**, in Key Engineering Materials, vol. 601, pp. 147-150, 2014, [://www.scientific.net/KEM.601.147.D](http://www.scientific.net/KEM.601.147.D).
20. Catana M., **Tarnita Daniela**, Tarnita D.N., **Modeling, Simulation and Optimization of a Human Knee Orthotic Device**, Applied Mechanics and Materials, Vol. 371 (2013), pp 549-553, Trans Tech Publications, Switzerland, doi:10.4028 /www.scientific.net/AMM.371.549
21. Catana M., **Tarnita Daniela**, Diorduc, V., **Virtual Simulation of Plastic Injection Technology for Medical Devices**, Applied Mechanics and Materials Vol. 371, 2013 pp 529-533, Trans Tech Publications, Switzerland, doi:10.4028 /www.scientific.net/AMM.371.529
22. **Tarnita Daniela**, Catana, M., Tarnita, D.N., **Nonlinear Analysis of Normal Human Gait for Different Activities with Application to Bipedal Locomotion**, Ro. J. Tech. Sci. Appl. Mech., Volume 58, N° 1-2, pp. 177–192, Bucharest, 2013, http://www.imsar.ro/RO_APPLIED_MECH_2013_nr1_2.pdf.
23. **Tarnita, D.** Tarnita, D.N., Boborelu, C., Catana, M., **Orthopaedic prototypes obtained by 3D printing technology**, Academic Journal of manufacturing engineering, vol. 11, issue 1, 2013, pp.119-124, www.eng.upt.ro/auif/Lucrari_PDF_2013_1/Tarnita.pdf.
24. Berceanu, C., **Tarnita, D.**, **Mechanical Design and Control Issues of a Dexterous Robotic Hand**, Advanced Materials Research Vols. 463-464 (2012) pp 1268-1271, Online available since 2012/Feb/10, (2012) doi:10.4028/www.scientific.net/AMR.463-464.1268, 2012.
25. Berceanu, C., **Tarnita, D.**, Filip, D., **Exteroceptive sensor system of a new developed artificial hand**, Journal of the Solid State Phenomena, Robotics and Automation Systems, Vol. 166-167, pp. 51-56, 2010, www.scientific.net/SSP.166.51.
26. Berceanu, C., **Tarnita, D.**, Filip, D., **About an experimental approach used to determine the kinematics of the human finger**, Journal of the Solid State Phenomena, Robotics and Automation Systems, Vol. 166-167, pp. 45-50, 2010, www.scientific.net/SSP.166.45.
27. Berceanu, C., **Tarnita, D.**, **Aspects Regarding the Fabrication Process of a New Fully Sensorized Artificial Hand**, MODTECH 2010: New face of TMCR, Proceedings of the International Conference ModTech, pp 123-126, 2010.
28. Berceanu, C., **Tarnita, D.**, **A new fabrication method for a computer controlled artificial hand with electric actuators**, International Journal of Modern Manufacturing Technologies, ISSN 2067–3604, Vol. I, No. 1 / 2009, pp 13, <http://www.modtech.tuiasi.ro/vol1no12009.php>.
29. **Tarniță, D.**, Boborelu, C., Popa, D., Berceanu, C., Tarniță, D. N., **Numerical simulations of the diaphyseal fractures of the human humerus bone using modular plates based on Nitinol**, Journal of Romanian Sports Medicine Society, Vol.VI, No2, pp.1380-1389, ISSN 1841-0162, http://www.medicinasportiva.ro/SRoMS/english/Journal/Sport_Medicine_Journal_No_18, 2009.
30. Berceanu, C., **Tarnita, D.**, **About the Kinematics and Control System of an Anthropomorphic Hand Usable as Prosthesis**, UPB Scientific Bulletin, Series D, Vol.73, Issue 1, 2011, ISSN 1454-2358, http://www.scientific_bulletin.upb.ro/SeriaD_-_Inginerie_Mecanica.php.

7.2.Chapters in books edit in International Publishing Houses:

1. **Tarnita D.**, Tarnita D.N, Bolcu, D., **Orthopedic implants based on shape memory alloys**, chapter in **Biomedical Engineering – From Theory to Applications**, in **InTech Publishing House**, Viena ISBN: 978-953-307-283-8, 2011, pp.431-468, <http://www.intechopen.com/books/references/biomedical-engineering-from-theory-to-applications/orthopaedic-modular-implants-based-on-shape-memory-alloys>.
2. Bizdoacă. N., **Tarniță, Daniela**, et al., **Biomimetic approach to design and control mechatronics structure using smart materials**, chapter in **"Robotics, Automation and Control"**, ISBN 978-953-7619-39-8, **InTech Publishing House**, pp 431-465, Viena, 2009, <http://www.intechopen.com/books/howtoreference/contemporary-robotics-challenges-and-solutions/biomimetic-approach-to-design-and-control-mechatronics-structure-using-smart-materials>.

7.3. Books in National Publishing Houses

1. **DANIELA TARNITA, DUMITRU BOLCU, *Elements of mechanics and strength of materials***, Universitaria Publishing House, Craiova, 2012.
2. **DANIELA TARNITA, *Elements of mechanical engineering and strength of materials***, Universitaria Publishing House, Craiova, 2012.
3. **DANIELA TARNIȚĂ - Mechanisms *actuated by springs. Methods for dynamic analysis and synthesis***, Universitaria Publishing House, Craiova, 1998.
4. **DUMITRU BOLCU, DANIELA TARNITA, *Methods for kinetostatics analysis of plane mechanisms***, EDP, Bucharest, 2009.
5. **DANIELA TARNITA, DUMITRU BOLCU, *Methods for kinematical analysis of planar mechanisms***, Didactic and Pedagogic Publishing House, Bucharest, 2005 ISBN 973-30-1485-0.
6. **DANIELA TARNIȚĂ -*Statistics. Theory and applications***, Universitaria Publishing House, Craiova, 2004.
7. **DUMITRU BOLCU, DANIELA TARNIȚĂ- *Elements for composite structures calculus and modeling***, Universitaria Publishing House, Craiova, 2001.

8. Member of the following professional associations:

Romanian Association of Mechanism and Machine Theory (**president-branch Craiova**);
 Romanian Association of Tensometry; Romanian Society of Biomaterials;
 Romanian Society of Theoretic and Applied Mechanics;
 Romanian Society of Robotics; Romanian Inventors Forum;

9. Member of the scientific and/or organizing committee for:

- IFToMM International Symposium on Science of Mechanisms and Machines, SYROM 2017
- President of International Conference of Mechanical engineering, 2015, Craiova;
- President of International Workshop “From Biological Systems to Robotic Structures” 2012
- Congress of Automotive, SMAT 2008, Craiova
- Advanced Concepts on Mechanical Engineering - ACME 2010, 2012, 2014, 2016, Iasi
- International Conference of Mechanical engineering, ICOME 2010, 2013, 2015, 2017, Craiova
- International Conference on Advancements of Medicine and Health Care through Technology, 2011
- MESROB -Medical and Service Robotics International Workshop–Lausanne 2014
- MESROB -Medical and Service Robotics International Workshop–Nantes 2015
- MESROB -Medical and Service Robotics International Workshop–Graz 2016
- MESROB -Medical and Service Robotics International Workshop–Casino 2018
- 21st Congress of the European Society of Biomechanics, July 5 - 8 2015, Prague, Czech Republic
- 1st Central & Eastern European Conference on Thermal Analysis and Calorimetry, 2011, Craiova

Member of Biomechanical Engineering Technical Committee of International Federation of Mechanism and Machines.

Member of Editorial Board for Journal of Rheumatic Diseases and Treatment- ClinMed International Library

Member of Editorial Board of Bulletin of The “Transilvania” University of Brasov, Series I Engineering Sciences.

10. Reviewer for: Robotics and Computer-Integrated Manufacturing, Transactions on Mechatronics, Revue Roumaine de Meccanique Appliquee, Australasian Physical & Engineering Sciences in Medicine Journal, Annals of Biomedical engineering, Springer Publishing House, Industrial Robot Journal, Proceedings of the Romanian Academy- Part A; Mechanical Sciences; Journal of Bionic Engineering; Journal of ASME; Key Engineering Materials, Applied Mechanics and Materials.

11. Experience in national or international projects:

Program / Project	Function	Period
Partner-ship Ford Romania – University of Craiova for transfer and implementation of Ford Eco-Technologies to realise of EcoSport model in Craiova- PN III Bridge Grant_BG92	Member	2016-2018

International Workshop “ From Biological Structures Inspiration to Robotic Structures”	Director	5-6 July 2012
Development of biomimetic design methodology with reverse engineering in cognitive recognition and control of biomimetic robots/ International Bilateral Project with Atilim University - Ankara – Turkey	member	2010-2011
Reverse Engineering in Cognitive Recognition And Control Of Biomimetics Structures, International Bilateral Project with Seoul National University	member	2010-2011
The knowledge of Universe: from reality to mental models. Program: Global perspective in Science and Spirituality Financed by John Templeton Foundation from USA, Partners: Elon University from USA; Universite Interdisciplinaire de Paris,	Local responsible in field	2006-2009
Memory: from individual to Society, from Quantum to Cosmos Program: METANEXUS GLOBAL NETWORK INITIATIVE Catalyst Grant Financed by John Templeton Foundation from USA	member	2009-2012
Modular adaptive orthopaedic implants based on smart materials –PNCDI Idei_92	director	2007-2010
The control and technological integration of the intelligent materials and structures CEEX –259–CITMSI, 2007, signed by CCMR- UCv,	Responsible in field	2006-2008
National technologic platform of spatial dynamics; CEEX- Stage III PC-D09-PT22-652, signed by National Institute of research and development for laser, plasma and radiation physics – INFLPR,	member	2005-2007
Parametric CAD/CAE system for simulation and analysis of the mechanical and kinematical characteristics of the human knee (CNCSIS)	director	2004-2005
Contribution on the analysis and synthesis of the mechanisms actuated by springs. No.14C/C12/1994. Contract signed with Education Ministry	director	1994

Grants in research-development of infrastructure - Structural Funds from EU

Program/Project	Responsibility	Period
Research Infrastructure for Applied Sciences –INCESA, University of Craiova	Head of Biomechanics Research Laboratory	2010-2015