

**Articole științifice publicate în reviste indexate Web of Science - Thomson**  
**Reuters (selecție)**

1. Dumitru, S, **Dumitru, N**, Copilusi, C, Rosca, AS, Computational Method for Dynamic Analysis of Multibody Systems with Deformable Elements, MATHEMATICS, 2797, *Category Quartile, Q<sub>1</sub>*,  
<http://dx.doi.org/10.3390/math13172797>
2. **Dumitru, N.**, Ciurezu-Gherghe, L., Copilusi, C., Geonea, I., & Dumitru, S. (2022). Theoretical and experimental study methods for a robotic system with deformable elements used in minimally invasive surgery. Mechanism and Machine Theory, 167, 104459, *Category Quartile, Q<sub>1</sub>*,  
<https://www.sciencedirect.com/science/article/pii/S0094114X21002172>
3. Copilusi, C., Dumitru, S., **Dumitru, N.**, Geonea, I., & Mic, C. (2024). An Exoskeleton Design and Numerical Characterization for Children with Duchenne Muscular Dystrophy. *Bioengineering*, 11(11), 1072.  
<https://pmc.ncbi.nlm.nih.gov/articles/PMC11591250/>, *Category Quartile Q2*
4. Dumitru, S., Constantin, A., Copilusi, C., & **Dumitru, N.** (2021). Impact Dynamics Analysis of Mobile Mechanical Systems. Mathematics, 9(15), 1776, *Category Quartile, Q<sub>1</sub>*  
<https://www.mdpi.com/2227-7390/9/15/1776>
5. Dumitru, S., Copilusi, C., **Dumitru, N.**, Geonea, I., (2024). A Dynamic Analysis of a Poly-Articulated Robot, Computation 12(8),156, *Category Quartile Q2*.  
<https://doi.org/10.3390/computation12080156>
6. Copilusi, C., Dumitru, S., Geonea, I., Ciurezu, L. G., & **Dumitru, N.** (2022). Design Approaches of an Exoskeleton for Human Neuromotor Rehabilitation. Applied Sciences, 12(8), 3952, *Category Quartile Q<sub>1</sub>*.  
<https://www.mdpi.com/2076-3417/12/8/3952>  
WOS:000787026200001
7. Bolcu, A., **Dumitru, N.**, Ciuca, I., Stanescu, M. M., & Bolcu, D. (2017). *The Vibrations Study of DAMMAR Based Composite Bars Reinforced with Natural Fibers by Using a New Euler-Bernoulli Theory*. MATERIALE PLASTICE, 54(3), 423-429,  
<http://www.revmaterialeplastice.ro/pdf/4%20BOLCU%20A%203%2017.pdf>  
WOS:000426412300004
8. Ciupitu, I., **Dumitru, N.**, & Teisanu, C. (2003). *Static analysis of the guiding bearing drill contact by finite element method*. Journal of materials processing technology, 143, 270-276. *Category Quartile, Q<sub>1</sub>*

<https://www.sciencedirect.com/science/article/pii/S0924013603004709>

WOS:000187510100052

9. Roșca, A., Dumitru, S., Catalu, D., **Dumitru, N.**, & Geonea, I. (2022). Dynamic motion analysis of a wheelchair for people with locomotor disabilities. Acta Technica Napocensis - series: Applied Mathematics, Mechanics, and Engineering, 65(2s), , Retrieved from <https://atna-mam.utcluj.ro/index.php/Acta/article/view/1921>
10. Calangiu, A., Dumitru, S., Copilusi, C., Rosca, A., Demian, M., & **Dumitru, N.** (2022). Optimizing in a dynamic mode the connecting rod from an internal combustion engine. Acta Technica Napocensis - Series: Applied Mathematics, Mechanics, and Engineering, 65(2S). Retrieved from <https://atna-mam.utcluj.ro/index.php/Acta/article/view/1901>
11. Ionică, v., **Dumitru, N.**, Geonea, I., & Bogdan, m. (2022). Modelling the vibratory effects of rail traffic on the environment. Acta Technica Napocensis - Series: Applied Mathematics, Mechanics, and Engineering, 65(2S). Retrieved from <https://atna-mam.utcluj.ro/index.php/Acta/article/view/1911>
12. Constantin, A., Oțat, O., Calangiu, A., Crăciunoiu, N., Margine, a., & **Dumitru, N.** (2022). The dynamic impact study of a crank connecting rod mechanism. Acta Technica Napocensis - series: Applied Mathematics, Mechanics, And Engineering, 65(2S). Retrieved from <https://atna-mam.utcluj.ro/index.php/Acta/article/view/1904>

### **Articole și publicații științifice indexate Web of Science - Thomson Reuters** **(WOS – selecție)**

1. Geonea, I., Copilusi, C., **Dumitru, N.**, Margine, A., Ciurezu, L., & Rosca, A. S. (2022, May). A New Exoskeleton Robot for Human Motion Assistance. In 2022 IEEE International Conference on Automation, Quality and Testing, Robotics (AQTR) (pp. 1-6). IEEE.  
<https://ieeexplore.ieee.org/abstract/document/9801965/>  
WOS:000890261900040
2. Ciurezu-Gherghe, L., **Dumitru, N.**, Geonea, D., & Bostina, S. (2022, May). Snake-Like Flexible Mechanical System With Applications in Exploratory Activities. In 2022 IEEE International Conference on Automation, Quality and Testing, Robotics (AQTR) (pp. 1-5). IEEE.  
<https://ieeexplore.ieee.org/abstract/document/9802035>  
WOS:000890261900043
3. Geonea, I., **Dumitru, N.**, Copilusi, C., & Margine, A. (2020, January). Experimental Determination of the Loading Capacity of the Elastic Bracelet Assembly. In IOP Conference Series: Materials Science and Engineering (Vol. 724, No. 1, p. 012006). IOP Publishing.  
<https://iopscience.iop.org/article/10.1088/1757-899X/724/1/012006/meta>  
WOS:000619349400006
4. **Dumitru N.**, Copilusi C., Calangiu A., Geonea I. (2020) An Engine Mechanism Dynamic Analysis by Considering the Kinematic Elements as Deformable Ones. In: Dumitru I.,

- Covaciu D., Racila L., Rosca A. (eds) The 30th SIAR International Congress of Automotive and Transport Engineering. SMAT 2019. Springer, Cham. [https://doi.org/10.1007/978-3-030-32564-0\\_2](https://doi.org/10.1007/978-3-030-32564-0_2)  
WOS:000528526600002
5. Bolcu A., **Dumitru N.**, Bolcu D., Miritoiu C.M., Stanescu M.M. (2020) A Study of the Mechanical Behavior of a Car Part Realized from Epoxy Resin Reinforced with Cotton Woven. In: Dumitru I., Covaciu D., Racila L., Rosca A. (eds) The 30th SIAR International Congress of Automotive and Transport Engineering. SMAT 2019. Springer, Cham. [https://doi.org/10.1007/978-3-030-32564-0\\_64](https://doi.org/10.1007/978-3-030-32564-0_64)  
WOS:000528526600064
  6. **Dumitru N.**, Geonea I., Copilusi C., Dumitru S., Otat O. (2019) Dynamic Models for Analyzing a Self-propelled Vehicle for People with Locomotor Disabilities. In: Burnete N., Varga B. (eds) Proceedings of the 4th International Congress of Automotive and Transport Engineering (AMMA 2018). AMMA2018 2018. Proceedings in Automotive Engineering. Springer, Cham. [https://doi.org/10.1007/978-3-319-94409-8\\_78](https://doi.org/10.1007/978-3-319-94409-8_78)  
WOS:000578264900078
  7. Ionut Geonea, **Nicolae Dumitru**, Cristian Copilusi, Ilie D., Otat O., Dragos Tutunea. (2019) Theoretical and Experimental Analysis for the Load Capacity of the Cone Tightening Assemblies. In: Burnete N., Varga B. (eds) Proceedings of the 4th International Congress of Automotive and Transport Engineering (AMMA 2018). AMMA2018 2018. Proceedings in Automotive Engineering. Springer, Cham. [https://doi.org/10.1007/978-3-319-94409-8\\_51](https://doi.org/10.1007/978-3-319-94409-8_51)  
WOS:000578264900051
  8. **Nicolae, Dumitru**, Sorin, Dumitru, Cristian, Copilusi, Cristina, Ploscaru (2018, May). A Reconfigurable Leg Exoskeleton for Human Locomotion Rehabilitation. In 2018 International Conference on Control, Artificial Intelligence, Robotics & Optimization (ICCAIRO) (pp. 95-102). IEEE.  
WOS:000493714800015  
<https://ieeexplore.ieee.org/stamp/stamp.jsp?arnumber=8698429>
  9. Geonea, I., **N. Dumitru**, and A. Margine. "*Analytical and Numerical Study of Critical Speed for Right Shafts.*" Acoustics and Vibration of Mechanical Structures—AVMS-2017. Springer, Cham, 2018. 411-417.  
[https://link.springer.com/chapter/10.1007/978-3-319-69823-6\\_49](https://link.springer.com/chapter/10.1007/978-3-319-69823-6_49)  
WOS:000437313600049
  10. Dumitru, S., Copilusi, C., & **Dumitru, N.** (2018, May). *A leg exoskeleton command unit for human walking rehabilitation.* In 2018 IEEE International Conference on Automation, Quality and Testing, Robotics (AQTR) (pp. 1-6). IEEE.  
<https://ieeexplore.ieee.org/abstract/document/8402732>  
WOS:000450065900033

11. Bolcu, A., **Dumitru, N.**, Ciuca, I., Stanescu, M. M., & Bolcu, D. (2017). *The Vibrations Study of DAMMAR Based Composite Bars Reinforced with Natural Fibers by Using a New Euler-Bernoulli Theory*. MATERIALE PLASTICE, 54(3), 423-429. **IF 1.248**  
<http://www.revmaterialeplastice.ro/pdf/4%20BOLCU%20A%203%2017.pdf>  
 WOS:000426412300004  
 $P1.4=3 \cdot (0,2+FI)/n=3 \cdot (0,2+1.248)/5=0.8688$
12. Geonea, Ionut, **Nicolae Dumitru**, and Ilie Dumitru. "Experimental and theoretical study of friction torque from radial ball bearings." IOP Conference Series: Materials Science and Engineering. Vol. 252. No. 1. IOP Publishing, 2017.  
<https://iopscience.iop.org/article/10.1088/1757-899X/252/1/012048/meta>  
 WOS:000419817200048
13. Marinescu, Gabriel Cătălin, Ștefan-Cristian Castravete, and **Nicolae Dumitru**. "Vibration study of a vehicle suspension assembly with the finite element method." IOP Conference Series: Materials Science and Engineering. Vol. 252. No. 1. IOP Publishing, 2017.  
<https://iopscience.iop.org/article/10.1088/1757-899X/252/1/012030/meta>  
 WOS:000419817200030
14. Oana, O., **Nicolae, Dumitru**, & Ilie, D. (2017, October). *Dynamic models to analyse the influence of the seat belt in a frontal collision*. In IOP Conference Series: Materials Science and Engineering (Vol. 252, No. 1, p. 012017). IOP Publishing.  
<https://iopscience.iop.org/article/10.1088/1757-899X/252/1/012017/meta>  
 WOS:000419817200017
15. **Dumitru, N.**, Copilusi, C., Geonea, I., & Margine, A. (2016, October). *Kinematic and Dynamic Study of a Mechanism for a Vehicle Front and Rear Stabilizer Bars*. In International Congress of Automotive and Transport Engineering (pp. 161-169). Springer, Cham.  
[https://link.springer.com/chapter/10.1007/978-3-319-45447-4\\_18](https://link.springer.com/chapter/10.1007/978-3-319-45447-4_18)  
 WOS:000390821400018
16. Oțăt, O. V., **Dumitru, N.**, Oțăt, V., & Dumitru, I. (2016, October). *Determination of Kinematic and Dynamic Behavior in the Driver's Skull upon the Impact with the Steering Wheel*. In International Congress of Automotive and Transport Engineering (pp. 812-819). Springer, Cham.  
[https://link.springer.com/chapter/10.1007/978-3-319-45447-4\\_89](https://link.springer.com/chapter/10.1007/978-3-319-45447-4_89)  
 WOS:000390821400089
17. Geonea, I., **Dumitru, N.** (2016). *Motion analysis of a robotic wheelchair*. In Advances in Robot Design and Intelligent Control (pp. 471-479). Springer, Cham.  
[https://link.springer.com/chapter/10.1007/978-3-319-21290-6\\_47](https://link.springer.com/chapter/10.1007/978-3-319-21290-6_47)  
 WOS:000381804400047

18. **Dumitru, N.**, Copilusi, C., & Ciortan, M. (2016). *Kinematic and Dynamic Study Contributions on Human Jaw System*. In *New Trends in Medical and Service Robots* (pp. 79-91). Springer, Cham.  
[https://link.springer.com/chapter/10.1007/978-3-319-23832-6\\_7](https://link.springer.com/chapter/10.1007/978-3-319-23832-6_7)  
WOS:000429272700007
19. Sorin, Dumitru., Dorian, C., Florin, M. L., **Nicolae, Dumitru**, & Valentin, G. (2015, October). *The experimental model of an forearm exoprosthesis*. In *System Theory, Control and Computing (ICSTCC), 2015 19th International Conference on IEEE*. (pp. 255-259).  
<https://ieeexplore.ieee.org/abstract/document/7321302>  
WOS:000382384100043
20. Geonea, I., **Dumitru, N.**, & Margine, A. (2015). *Design and motion study of a wheelchair for disabled people*, WORLD CONGRESS ON ENGINEERING, WCE 2015, VOL II Book Series: Lecture Notes in Engineering and Computer Science Pages: 1028-1033.  
[http://www.iaeng.org/publication/WCE2015/WCE2015\\_pp1028-1033.pdf](http://www.iaeng.org/publication/WCE2015/WCE2015_pp1028-1033.pdf)  
WOS:000380592500067
21. **Dumitru, N.**, Dumitru, S., Copilusi, C., Semenescu D., & Geonea, I. (2015). *Modal dynamic analysis of the wicket gate mechanism from a hydraulic turbine*. In *Proceedings of the World Congress on Engineering (Vol. 2). Lecture Notes in Engineering and Computer Science* 2218, pp. 1213-1218.  
[http://www.iaeng.org/publication/WCE2015/WCE2015\\_pp1213-1218.pdf](http://www.iaeng.org/publication/WCE2015/WCE2015_pp1213-1218.pdf)  
WOS:000380592500102
22. Geonea, I., Ungureanu, A., **Dumitru, N.**, & Racilă, L. (2015). *Dynamic Modelling of a Four Legged Robot*. In *New Trends in Mechanism and Machine Science* (pp. 147-155). Springer, Cham.  
[https://link.springer.com/chapter/10.1007/978-3-319-09411-3\\_16](https://link.springer.com/chapter/10.1007/978-3-319-09411-3_16)  
WOS:000357867900016
23. **Dumitru, N.**, Craciunoiu, N., Malciu, R., & Ploscaru, N. (2015). *Elastodynamic analysis of the sucker rod pumping system mechanism*. In *New Trends in Mechanism and Machine Science* (pp. 355-363). Springer, Cham.  
[https://link.springer.com/chapter/10.1007/978-3-319-09411-3\\_38](https://link.springer.com/chapter/10.1007/978-3-319-09411-3_38)  
WOS:000357867900038
24. Ciunel, S., Popa, D. L., & **Dumitru, N.** (2013). *Studies about Movement Biofidelity of a Dummy Neck Used in an Impact Testing Device*. In *Applied Mechanics and Materials (Vol. 371, pp. 539-543)*. Trans Tech Publications.  
<https://www.scientific.net/amm.371.539>  
WOS:000334556900105

25. **Dumitru, N.**, Malciu, R., Calbureanu, M., Dumitru, S., & Marinescu, G. C. (2012). *Dynamic Analysis of a Mobile Mechanical System with Deformable Elements*. In Advanced Materials Research (Vol. 463, pp. 1242-1245). Trans Tech Publications.  
<https://www.scientific.net/AMR.463-464.1242>  
 WOS:000308114100244
  
26. Copilusi, C., Grecu, V., & **Dumitru, N.** (2013). *Human upper limb robotic system experimental analysis by using Contemphas motion software*. In Applied Mechanics and Materials (Vol. 325, pp. 1062-1066). Trans Tech Publications.  
<https://www.scientific.net/AMM.325-326.1062>  
 WOS:000400801300006
  
27. **Dumitru, N.**, Copilusi, C., Marin, M., & Rusu, L. (2010). *Human Lower Limb Dynamic Analysis with Applications to Orthopedic Implants*. In New Trends in Mechanism Science (pp. 327-334). Springer, Dordrecht.  
[https://link.springer.com/chapter/10.1007/978-90-481-9689-0\\_38](https://link.springer.com/chapter/10.1007/978-90-481-9689-0_38)  
 WOS:000395597100038
  
28. **Dumitru, N.**, Malciu, R., & Geonea, I. (2010). *Differential transmission for robotizing a powered wheelchair*. Proceedings of the OPTIROB, 47-51.  
[http://rpsonline.com.sg/proceedings/9789810858407/978-981-08-5840-7\\_S1-10.xml](http://rpsonline.com.sg/proceedings/9789810858407/978-981-08-5840-7_S1-10.xml)  
 WOS:000392682500009
  
29. **Nicolae Dumitru**, Danel Semenescu, Nicolae Craciunoiu, Daniela Vintila and Ionut Geonea, *On the Modeling of a Hydraulic Turbine Directory Apparatus*, Proceedings Of The Fifth International Conference On Optimization Of The Robots And Manipulators, 2010 Pages: 75-80 Published: 2010.  
[http://rpsonline.com.sg/proceedings/9789810858407/978-981-08-5840-7\\_S2-5.xml](http://rpsonline.com.sg/proceedings/9789810858407/978-981-08-5840-7_S2-5.xml)  
 WOS:000392682500014
  
30. **Dumitru, N.**, Negru, M., & Dumitru, S. (2010). *Simulation of a pressure controlled hose type joint using FEM*. In SYROM 2009 (pp. 549-562). Springer, Dordrecht.  
[https://link.springer.com/chapter/10.1007/978-90-481-3522-6\\_46](https://link.springer.com/chapter/10.1007/978-90-481-3522-6_46)  
 WOS:000289492600046
  
31. Copilusi, C., **Dumitru, N.**, Rusu, L., & Marin, M. (2010, June). *Cam mechanism kinematic analysis used in a human ankle prosthesis structure*. In World Congress on Engineering, London, UK, June (pp. 1316-1320).  
[http://www.iaeng.org/publication/WCE2010/WCE2010\\_pp1316-1320.pdf](http://www.iaeng.org/publication/WCE2010/WCE2010_pp1316-1320.pdf)  
 WOS:000394059900100
  
32. Grecu, V., **Dumitru, N.**, & Grecu, L. (2009, March). *Analysis of human arm joints and extension of the study to robot manipulator*. In Proceedings of the International MultiConference of Engineers and Computer Scientists (Vol. 2, pp. 18-20).  
[http://www.iaeng.org/publication/IMECS2009/IMECS2009\\_pp1348-1351.pdf](http://www.iaeng.org/publication/IMECS2009/IMECS2009_pp1348-1351.pdf)  
 WOS:000266097201035

33. **Dumitru, N.**, Copilusi, C., & Zuhair, A. (2009, July). *Dynamic Modeling of a Mobile Mechanical System with Deformable Elements*. WORLD CONGRESS ON ENGINEERING 2009, VOLS I AND II Book Series: Lecture Notes in Engineering and Computer Science Pages: 1569-+ Published: 2009.  
[http://iaeng.org/publication/WCE2009/WCE2009\\_pp1569-1574.pdf](http://iaeng.org/publication/WCE2009/WCE2009_pp1569-1574.pdf)  
WOS:000271615700291

### **Articole și publicații științifice BDI, (SCOPUS și WOS) – selecție**

1. **Dumitru, N.** Dumitru, S. Copilusi, C. Geonea, I. Catalu, D. Structural Kinematic Analysis of a Wheelchair Mechanism Designed for Disabled Persons. Lecture Notes in Mechanical Engineering Pages 59 – 70. 2024 3rd International Conference on Innovation in Engineering, ICIE 2024 Povoação 26 June 2024 through 28 June 2024.  
[https://link.springer.com/chapter/10.1007/978-3-031-61575-7\\_6](https://link.springer.com/chapter/10.1007/978-3-031-61575-7_6)
2. Geonea, I., **Dumitru, N.**, Dumitru, S., Copilusi, C., Tarnita, D. (2024). Structural Solutions of Walking Mechanisms Intended to Exoskeleton Robots to Assist Human Gait. In: Lovasz, EC., Ceccarelli, M., Ciupe, V. (eds) Mechanism Design for Robotics. MEDER 2024. Mechanisms and Machine Science, vol 166. Springer, Cham.  
[https://link.springer.com/chapter/10.1007/978-3-031-67383-2\\_26#citeas](https://link.springer.com/chapter/10.1007/978-3-031-67383-2_26#citeas)
3. **Dumitru, N.**, Dragut, E., Craciunoiu, N., & Geonea, I. (2018). *Experimental Bench for Spur Gears Efficiency Measurement*. In New Advances in Mechanism and Machine Science (pp. 477-485). Springer, Cham.  
[https://link.springer.com/chapter/10.1007/978-3-319-79111-1\\_47](https://link.springer.com/chapter/10.1007/978-3-319-79111-1_47)
4. **Dumitru, N.**, Copilusi, C., Dumitru, S., Rosu, E., *Design of a reconfigurable exoskeleton used on human locomotion recovery*, International Journal of Mechanics 12, pp. 150-161, 2018.  
<http://www.naun.org/main/NAUN/mechanics/2018/a382003-abn.pdf>
5. **Dumitru N.**, Copilusi C., Dumitru S., Rusu L., Rosu E., *A Knee Exoskeleton Mechanism Dynamic Analysis*, Proceedings of the World Congress on Engineering and Computer Science 2018 Vol II, WCECS 2018, October 23-25, 2018, San Francisco, USA.  
[http://www.iaeng.org/publication/WCECS2018/WCECS2018\\_pp552-557.pdf](http://www.iaeng.org/publication/WCECS2018/WCECS2018_pp552-557.pdf)
6. **Dumitru, N.**, Craciunoiu, N., Geonea, I., & Copilusi, C. (2017). *Elastodynamic Analysis of a Mechanism with Flexible Links*. Lecture Notes in Engineering and Computer Science, 2230, pp. 821-828.  
[http://www.iaeng.org/publication/WCE2017/WCE2017\\_pp821-828.pdf](http://www.iaeng.org/publication/WCE2017/WCE2017_pp821-828.pdf)
7. **Dumitru, N.**, & Dumitru, V. C. (2014). *Mechatronic System with Applications in Medical Robotics*. In The 11th IFToMM International Symposium on Science of Mechanisms and Machines (pp. 371-379). Springer, Cham.  
[https://link.springer.com/chapter/10.1007/978-3-319-01845-4\\_37](https://link.springer.com/chapter/10.1007/978-3-319-01845-4_37)
8. **Dumitru, N.**, Malciu, R., Calbureanu, M., *A finite element formulation for the elastodynamic analysis of mobile mechanical systems*, International Journal of Mathematical Models and Methods in Applied Sciences, 7(7), pp. 708-716, 2013.  
<http://www.naun.org/main/NAUN/ijmmas/g052001-240.pdf>

9. **Dumitru, N.**, Malciu, R., Grecu, V., *Theoretical and experimental study of the human upper limb dynamic behavior*, Advanced Materials Research 748, pp. 759-764, 2013.  
<https://www.scientific.net/AMR.748.759>  
<http://toc.proceedings.com/17866webtoc.pdf>
10. **Dumitru, N.**, Copilusi, C., Geonea, I., Tarnita, D., & Dumitrache, I. (2015). *Dynamic analysis of an exoskeleton new ankle joint mechanism*. In New Trends in Mechanism and Machine Science (pp. 709-717). Springer, Cham.  
[https://link.springer.com/chapter/10.1007/978-3-319-09411-3\\_75](https://link.springer.com/chapter/10.1007/978-3-319-09411-3_75)
11. Geonea, I., **Dumitru, N.**, Tarnita, D., Copilusi, C., & Rosca, A. S. (2020, July). Design and Motion Analysis of an Exoskeleton Robot for Assisting Human Locomotion. In International Workshop on Medical and Service Robots (pp. 44-52). Springer, Cham.  
[https://link.springer.com/chapter/10.1007/978-3-030-58104-6\\_6](https://link.springer.com/chapter/10.1007/978-3-030-58104-6_6)
12. Copilusi, C., **Dumitru, N.**, Margine, A., Geonea, I., Rosca, A. S., & Rosu, E. (2020, July). Method for 3D Modeling of Human Osteo-Articular System Bones. In International Workshop on Medical and Service Robots (pp. 298-305). Springer, Cham.  
[https://link.springer.com/chapter/10.1007/978-3-030-58104-6\\_34](https://link.springer.com/chapter/10.1007/978-3-030-58104-6_34)
13. Geonea, I. D., **Dumitru, N.**, Copilusi, C., Margine, A., Ciurezu, L., & Didu, A. (2020, May). New design and motion analysis of an exoskeleton robot for assisting human locomotion. In 2020 IEEE International Conference on Automation, Quality and Testing, Robotics (AQTR) (pp. 1-6). IEEE.
14. Copilusi, C., **Dumitru, N.**, Margine, A., Rosca, A., & Rosu, E. (2020). A Child Orthosis Design and Simulation Based on Dynamic Considerations. In The 10th International Conference on Engineering, Project, and Production Management (pp. 497-509). Springer, Singapore.  
[https://link.springer.com/chapter/10.1007/978-981-15-1910-9\\_41](https://link.springer.com/chapter/10.1007/978-981-15-1910-9_41)
15. Copilusi, C., **Dumitru, N.**, Margine, A., & Geonea, I. (2019, August). Dynamic Analysis of a Human Ankle Joint Prosthesis. In IOP Conference Series: Materials Science and Engineering (Vol. 568, No. 1, p. 012077). IOP Publishing.  
<https://iopscience.iop.org/article/10.1088/1757-899X/568/1/012077/meta>
16. Geonea, I., **Dumitru, N.**, Rosca, A., Craciunoiu, N., Racila, L., & Copilusi, C. (2019, August). Computation of a torsion spring stabilizer bar rigidity and fatigue resistance. In IOP Conference Series: Materials Science and Engineering (Vol. 568, No. 1, p. 012013). IOP Publishing.  
<https://iopscience.iop.org/article/10.1088/1757-899X/568/1/012013/meta>
17. Didu, A., **Dumitru, N.**, & Calangiu, A. M. (2019, May). Thermally coupled structural analysis of a connecting rod obtained by powder metallurgy. In IOP Conference Series: Materials Science and Engineering (Vol. 514, No. 1, p. 012030). IOP Publishing.  
<https://iopscience.iop.org/article/10.1088/1757-899X/514/1/012030/meta>
18. Geonea, I., **Dumitru, N.**, Tarnita, D., & Rinderu, P. (2019, June). Design and kinematics of a new leg exoskeleton for human motion assistance. In IFToMM World Congress on Mechanism and Machine Science (pp. 165-174). Springer, Cham.  
[https://link.springer.com/chapter/10.1007/978-3-030-20131-9\\_17](https://link.springer.com/chapter/10.1007/978-3-030-20131-9_17)
19. Geonea, I., **Dumitru, N.**, Rinderu, P., & Margine, A. (2018). Design Solutions for Human Legs Motion Assistance Exoskeletons. In Proceedings of the World Congress on Engineering (Vol. 2).  
[http://www.iaeng.org/publication/WCE2018/WCE2018\\_pp783-788.pdf](http://www.iaeng.org/publication/WCE2018/WCE2018_pp783-788.pdf)

20. Geonea, I., **Dumitru, N.**, Rosca, A., & Didu, A. (2018). *Design, Numerical Simulation and Manufacturing of a Powered Wheelchair*. In New Advances in Mechanism and Machine Science (pp. 191-199). Springer, Cham.  
[https://link.springer.com/chapter/10.1007/978-3-319-79111-1\\_19](https://link.springer.com/chapter/10.1007/978-3-319-79111-1_19)
21. Ciurezu-Gherghe, L., **Dumitru, N.**, & Copilusi, C. (2018). *Design and Simulation of a Snake like Robot*. In New Advances in Mechanism and Machine Science (pp. 263-272). Springer, Cham.  
[https://link.springer.com/chapter/10.1007/978-3-319-79111-1\\_26](https://link.springer.com/chapter/10.1007/978-3-319-79111-1_26)
22. Copilusi, C., **Dumitru, N.**, & Margine, A. (2018). *Children Locomotion Rehabilitation Test Bed Designed from Kinematic Considerations*. In New Advances in Mechanism and Machine Science (pp. 171-179). Springer, Cham.  
[https://link.springer.com/chapter/10.1007/978-3-319-79111-1\\_17](https://link.springer.com/chapter/10.1007/978-3-319-79111-1_17)
23. Oțăt, O.V., **Dumitru, N.**, Oțăt, V., *The kinematic behaviour of the driver and the degree of injuries in vehicle frontal collision*, International Journal of Mathematics and Computers in Simulation, 10, pp. 53-62, 2016.  
<http://www.naun.org/main/NAUN/mcs/2016/a162002-252.pdf>
24. Copilusi, C., Ceccarelli, M., **Dumitru, N.**, & Carbone, G. (2014). *Design and simulation of a leg exoskeleton linkage for a human rehabilitation system*. In The 11th IFToMM international symposium on science of mechanisms and machines (pp. 117-125). Springer, Cham.  
[https://link.springer.com/chapter/10.1007/978-3-319-01845-4\\_12](https://link.springer.com/chapter/10.1007/978-3-319-01845-4_12)
25. Geonea, I. D., Margine, A., **Dumitru, N.**, & Copilusi, C. (2014). *Design and Simulation of a Mechanism for Human Leg Motion Assistance*. In Advanced Materials Research (Vol. 1036, pp. 811-816). Trans Tech Publications.  
<https://www.scientific.net/AMR.1036.811>
26. Marinescu, G. C., **Dumitru, N.**, & Geonea, I. (2013). *Dynamic Modelling and Simulation of an Auto Vehicle Steering Mechanism Considering its Elements as Flexible*. In Applied Mechanics and Materials (Vol. 245, pp. 150-155). Trans Tech Publications.  
<https://www.scientific.net/AMM.245.150>
27. Copilusi, C., **Dumitru, N.**, Margine, A., *Modular knee orthosis fem analysis from kinematic considerations*, Mechanisms and Machine Science, 7, pp. 431-439, 2013.  
[https://link.springer.com/chapter/10.1007/978-94-007-4902-3\\_46](https://link.springer.com/chapter/10.1007/978-94-007-4902-3_46)
28. Copilusi, C., Marin, M., **Dumitru, N.**, & Rusu, L. (2012). *Locomotion System Dynamic Analysis with Application on Children Orthotics and Prostheses Devices*. In World Congress on Engineering. Lecture Notes in Engineering and Computer Science, 3, pp. 1663-1668.  
[http://www.iaeng.org/publication/WCE2012/WCE2012\\_pp1663-1668.pdf](http://www.iaeng.org/publication/WCE2012/WCE2012_pp1663-1668.pdf)

### **Brevete de inventii**

1.Exoskeleton-type system to assist locomotion in locomotor-disabled persons, has elements leading mechanisms for right leg and left leg which are actuated by electric motor which transmits movement to axle. Autori: DUMITRU N, GEONEA I D, DUMITRU S, COPILUSI P C, CIUREZU-GHERGHE L. Anul publicarii:2020. Nr. RO134430-A1.

Link:

<https://www.webofscience.com/wos/alldb/full-record/DIIDW:2019839404>

2. Robotic system for neuro-motor rehabilitation for functional recovery of person, has elements that are articulated to one another by some kinematic rotation couples, and movement of three actuators are placed on frame by chain transmissions. Autori: DUMITRU N, COPILUSI P C, DUMITRU S, GEONEA I D, ROSU E. Nr. RO134022-A2.

Link:

<https://www.webofscience.com/wos/alldb/full-record/DIIDW:202036417K>

3. Exoskeleton type mechatronic system for assisting walking of locomotor disabled persons, has elements whose lengths are adjustable depending on anthropomorphic dimensions of subjects, and structure that consists of mobile kinematic elements. Autori: Geonea I., Dumitru N., Dumitru S., Copilusi C., Ciurezu – Gherghe L. Nr. RO134430-A1/RO134430-B1.

Link:

<https://www.webofscience.com/wos/alldb/full-record/DIIDW:202097272M>

4. Exoskeleton intended for the rehabilitation of human locomotion, has mechanism having role of actuating ankle and leg and that consists of number of nine kinematic mobile elements of bar type, with rectangular cross-section. Autori: Copilusi C., Geonea I., Dumitru N., Margine Al., Dumitru S., Ciurezu – Gherghe L. Nr. RO135806-A0.

Link <https://www.webofscience.com/wos/alldb/full-record/DIIDW:2022B3284X>

5. Brevet, nr. A 00147 din 2019, Exoschelet destinat asistării mersului uman și reabilitării, data de depozit, 05.03.2019. Titular-Universitatea din Craiova. **Acordat prin hotărârea OSIM 4.3/35 din 29.01.2021. Patent Number: RO134430-A1**

Inventatori: Geonea Ionut, **Nicolae Dumitru**, Sorin Dumitru, Cristian Copiluși, Ciurezu Gherghe Leonard,

<https://patents.google.com/patent/RO134430A1/ro?q=Patent+Number:+RO134430-A1>

### **Produse, tehnologii, platforme și servicii inovative** **Coordonator/prim autor**

1. Sistem Robotic Destinat Reabilitării Locomotiei Persoanelor cu Deficiente Neuromotorii (acronim: NeuRob), Cerere de brevet 16/18.10.2018. OSIM cu Nr. A/00816/18.10.2018.

2. Vehicul robotizat pentru deservirea persoanelor cu deficiențe locomotorii.